

# Motion Reference Units

*High performance, Affordable and Robust*

 MRU Compact



 MRU Marine



 MRU Subsea



 MRU Ex





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# Our advantages



## High Accuracy

An MRU from Norwegian Subsea has robust and high-performance motion measurements even in irregular motions and during horizontal accelerations.

Other MRUs may perform well in regular motions, such as in single frequency sine wave motion in lab conditions, but a Norwegian Subsea MRU gives you the performance you need in real sea conditions.

## Affordable

High performance in all conditions at affordable prices set the Norwegian Subsea MRUs apart from the competition.

## Easy to use

Our small and lightweight MRUs, with flexible cable options, are easy to install and come with free web browser configuration software for effortless integration into your system.

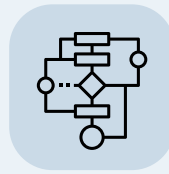
## How do we achieve this?



### MEMS sensors

Advances in MEMS technology gyroscopes and accelerometers enable new high accuracy sensors at low cost

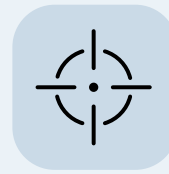
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### Sensor Fusion Algorithms

Our unique advanced sensor fusion algorithms get the most out of the best available sensors to provide great results under realistic circumstances

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### The Result: High Accuracy at low cost

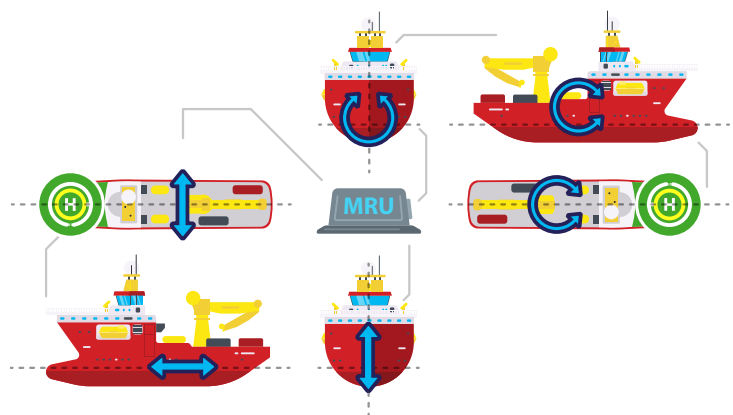
High Accuracy in Real Sea Conditions

## What is a Motion Reference Unit?

### Motion Reference Units designed for your needs

A Motion Reference Unit (MRU) is a self-contained sensor that measures motion in all 6 degrees of freedom (DoF): Roll, Pitch, Yaw, Surge, Sway, and Heave. The 6 DoF positions, velocities and accelerations are measured by the MRU using high-end gyroscopes and accelerometers together with advanced sensor fusion algorithms.

An MRU has high accuracy Roll & Pitch measurements, and measures oscillatory Heave, Surge and Sway motions for wave periods at sea. Linear motions with very long periods, or steps, cannot be measured by an MRU as it assumes a 0 mean heave position.



# Product overview



The Norwegian Subsea range of MRUs covers most marine and subsea applications.

The Compact, Marine, Subsea and Ex models have different mechanical and electrical interfaces suitable for your environment, whether installation is in a cabinet, on deck or at the bottom of the ocean.

Each model is available in the 3000, 6000 and 9000 series, to accommodate different accuracy requirements. All MRU models are available in the inclinometer/VRU version if you only need attitude measurements (Roll & Pitch).

All Norwegian Subsea sensors can be mounted in any position.

## MRU Compact



**Usage area**  
IP65

**Heave accuracy**  
5.0 cm or 5.0 %

### Roll & Pitch accuracy

- ↗ **3000** ± 0.05°
- ↗ **6000** ± 0.02°
- ↗ **9000** ± 0.01°

**Connectors**  
RJ45 or RJ50

## MRU Marine



**Usage area**  
On deck, 50 m depth

**Heave accuracy**  
5.0 cm or 5.0 %

### Roll & Pitch accuracy

- ↗ **3000** ± 0.05°
- ↗ **6000** ± 0.02°
- ↗ **9000** ± 0.01°

**Connectors**  
Lemo or Subconn

## MRU Subsea



**Usage area**  
6000 m depth

**Heave accuracy**  
5.0 cm or 5.0 %

### Roll & Pitch accuracy

- ↗ **3000** ± 0.05°
- ↗ **6000** ± 0.02°
- ↗ **9000** ± 0.01°

**Connectors**  
Subconn

## MRU Ex



**Usage area**  
Hazardous areas

**Heave accuracy**  
5.0 cm or 5.0 %

### Roll & Pitch accuracy

- ↗ **3000** ± 0.05°
- ↗ **6000** ± 0.02°
- ↗ **9000** ± 0.01°

**Connectors**  
Pigtail cable

## Which series should I choose?

This depends on your application, here are some general guidelines.

### ↗ 3000

The 3000 series, with 0.05° accuracy in Roll & Pitch, is ideal for most **monitoring applications** where the main purpose is to collect motion data for analysis or decision making. This model is also suitable for some control applications, such as AHC for smaller vessels with short lever arms to the remote monitoring points.

### ↗ 6000

The 6000 series, with 0.02° accuracy in Roll & Pitch, is our most versatile MRU due to its high accuracy and is suitable for most applications. This is the recommended MRU for most **control applications** such as AHC and winch control.

### ↗ 9000

The 9000 series, with 0.01° accuracy in Roll & Pitch is our most accurate MRU. We recommend this MRU for **sensor compensation applications** such as hydrography, and for **advanced control applications** such as 3D motion compensated gangways.

# Applications

Norwegian Subsea Motion Reference Units (MRUs) can be used in a variety of Marine, Subsea and Wind Energy applications.

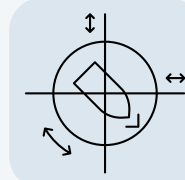


## Marine Operations



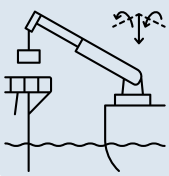
### **Ship Monitoring**

Prevent Cargo damage and Container loss.  
Add accurate ship motion measurements for safe and optimal vessel operations.



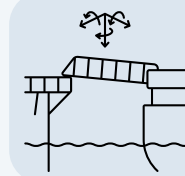
### **Dynamic Positioning**

Motion compensation of GNSS antenna and other position reference systems.  
Easy MRU retrofit and no recalibration.



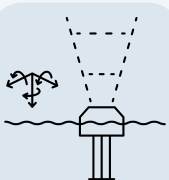
### **Active Heave Compensation**

Heave compensation of cranes, LARS and winches requires accurate heave measurements in Real sea conditions.



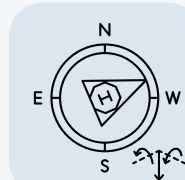
### **Gangway**

3D motion compensated gangways require accurate 6DoF motion measurements at all times in Real sea conditions.



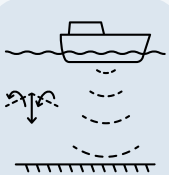
### **Wind Lidar Buoys**

High quality wind data requires accurate heave, roll and pitch measurements in Real sea conditions.



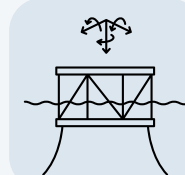
### **Helideck Monitoring**

Accurate Heave velocity and roll and pitch measurements in Real sea conditions.  
No recalibration and flawless operation in any temperature.



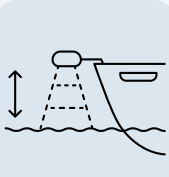
### **Hydrography**

Accurate motion compensation of Sonars, ensuring high-quality seafloor maps.  
Compact and cost-effective MRU.



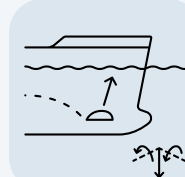
### **Offshore Fish Farms**

Condition monitoring of Offshore fish farms.  
Reduce risk with Accurate motion measurements.



### **Wave Radar**

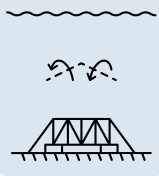
Accurate heave measurements to compensate downward looking wave radars. Compact and no recalibration required.



### **Stabilizing Fins**

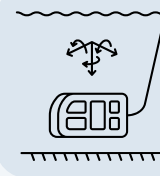
Roll damping systems and Stabilizing fins need accurate and affordable roll measurements in Real sea conditions.

# Subsea



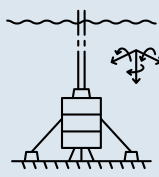
## **Subsea Surveys**

Precise subsea tilt (roll & pitch) measurements at affordable prices.



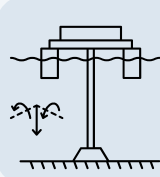
## **ROV/AUV**

Reliable and accurate motion measurements for navigation and payload sensor compensation.



## **BOP Monitoring**

Accurate 6DoF motion and vibration measurements to monitor BOP and other subsea structures.



## **Riser Monitoring**

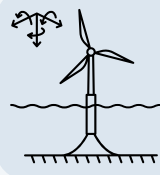
Topside motion sensors as input to the riser digital twin or subsea sensors attached to the riser.

# Wind Energy



## **Bottom Fixed Offshore Wind**

Turbine tower roll & pitch measurements as input to a wind tower digital twin model. Ultra-low-noise accelerometer for structural monitoring.



## **Floating Wind Turbine Control**

Accurate MRU measurements used in active pitch control to limit wave induced motions.



## **Floating Wind Base Motion Monitoring**

Structural monitoring of the floating wind base and mooring system using MRUs and Ultra-low-noise accelerometers.

# MRU Compact



### Compact

The MRU Compact is compact, dust and splash proof and is suitable for mounting indoors or inside a control box.

### Plug & Play

The MRU Compact is plug & play due to the standard RJ 45 ether-net connector with passive power over ethernet (PoE). This makes cabling very fast & easy. The MRU comes with a wide range of standard and customized data protocols. Integration is never an issue.

### Heave accuracy

5.0 cm or 5.0 %

### Available models

3000   6000   9000  
 $\pm 0.05^\circ$     $\pm 0.02^\circ$     $\pm 0.01^\circ$   
 Roll & Pitch accuracy

	RJ45	RJ50
Environment	IP65	
Connector	RJ45 with POE	10-pin RJ50 with POE
Ports	Ethernet	Ethernet & RS-232 / Ethernet & RS-485 / Ethernet & PPS
Communication	Ethernet: UDP, Modbus TCP, Ethernet/IP	
Weight	0.55 kg	
Footprint (L x B x H)	12.0 cm x 5.7 cm x 5.3 cm	
Enclosure material	Anodized aluminum 6061-T6	
Operating temperature range	-40 to +85 degrees Celsius	
Options	Magnetic Heading, Inclinometer / VRU version	

### What is passive Power over Ethernet?

Passive Power over Ethernet means that the MRU Compact is powered through the Ethernet cable with 9 - 36 V DC. Please note that active PoE switches do not work with passive PoE devices like the MRU Compact.

We recommend using a PoE splitter / injector to power the MRU Compact.

### Versions and Options

The MRU is also available in an inclinometer / VRU version without Heave/Surge/Sway output, which gives the same Roll & Pitch performance as the MRU, also in irregular coupled motions.



**Versatile placement**

The MRU Marine can be used on deck or under water in up to 50 m water depth (MRU Marine SW). The MRU Marine comes with ethernet, RS232, RS485 and PPS time synchronization ports for easy communication with your system. Connection through custom length pig-tail cables with or without junction box.

**Versatile connectivity**

Industrial communication protocols (Modbus TCP, Ethernet/IP, Modbus RTU, etc.) can be used for PLC interfacing. The MRU comes with a wide range of standard and customized data protocols in ASCII or binary formats.

**Heave accuracy**

5.0 cm or 5.0 %

**Available models**

3000	6000	9000
± 0.05°	± 0.02°	± 0.01°
Roll & Pitch accuracy		

	Marine	Marine SW	
Environment	IP68	50 m water depth	
Connector	Marine 16 pin male connector	8 pin SubConn MCBH8M	16 pin SubConn MCBH16M
Ports	Ethernet, RS-232, RS-485, PPS	Ethernet & RS-232 / Ethernet & 2-wire RS-485	Ethernet, RS-232, RS-485, PPS
Communication	Ethernet: UDP, Modbus TCP, Ethernet/IP. RS-485: Modbus RTU		
Weight	1.2 kg		
Footprint (L x B x H)	15.4 cm x 8.6 cm x 6.7 cm		
Enclosure material	Anodized aluminum 6061-T6		
Operating temperature range	-40 to +85 degrees Celsius		
Options	Magnetic Heading, Inclinometer / VRU version		

**Analog outputs**

Analog outputs are available using the analog output junction box. Configurable +/-10 V and 4-20 mA output signals are available.

**Retrofit**

Norwegian Subsea MRUs are often used as a drop-in replacement of older MRUs (retrofit) on Dynamic Positioning, Helideck Monitoring and Active Heave Compensation systems. For these applications, normally no recalibration is required.

**Versions and Options**

The MRU is also available in an inclinometer / VRU version without Heave/Surge/Sway output, which gives the same Roll & Pitch performance as the MRU, also in irregular coupled motions.





**6000 m water depth rating**

The MRU Subsea is ideal for use in subsea applications such as riser motion monitoring, ROV/ AUV or subsea surveys. The titanium casing is very compact and depth-rated to 6000 m! The small size and footprint make it easy to install almost anywhere. It is equipped with a Subconn wet-mate-able connector.

The Subsea Inclinometer version is popular due to its small size, high accuracy, and affordability.

All Norwegian Subsea sensors can be mounted in any position.

**Heave accuracy**

5.0 cm or 5.0 %

**Available models**

3000	6000	9000
± 0.05°	± 0.02°	± 0.01°
Roll & Pitch accuracy		

<i>Subsea</i>	
Environment	6000 m water depth
Connector	8-pin SubConn FCR1508M
Ports	Ethernet & RS-232 Ethernet & 2-wire RS-485
Communication	Ethernet: UDP, Modbus TCP, Ethernet/IP
Weight	1.6 kg
Footprint (L x B x H)	7.6 cm x 7.6 cm x 16.5 cm
Enclosure material	Titanium housing
Operating temperature range	-40 to +70 degrees Celsius
Options	Magnetic Heading, Inclinometer / VRU version

**Easy interfacing**

The MRU Subsea comes in a 6000 m rated titanium housing with ethernet and serial ports for easy communication with your system. Industrial communication protocols can be used for PLC interfacing. The MRU comes with a wide range of standard and customized ASCII or binary data protocols. The MRU can be delivered with custom length cables with Subconn 8 pin connectors.

**Versions and Options**

The MRU is also available in an inclinometer / VRU version without Heave/Surge/Sway output, which gives the same Roll & Pitch performance as the MRU, also in irregular coupled motions.



**For Hazardous Areas**

The Ex MRU is a cost-effective solution for hazardous areas. Easy to install with pigtail cable and including all certificates and documentation.

- Ex certificate II 2 G Ex d IIC Gb
- Compact and cost effective unit
- Stainless steel unit
- Ethernet & serial line

**Versions and options**

- Including pigtail cable in custom lengths

**Heave accuracy**

5.0 cm or 5.0 %

**Available models**

3000
6000
9000

± 0.05°    ± 0.02°    ± 0.01°

Roll & Pitch accuracy



**MRU Ex**

Environment	II 2 G Ex d IIC Gb
Connector	Pigtail cable - 8 wires 10 m / 25 m / custom length
Ports	Ethernet & RS-232 Ethernet & 2-wire RS-485
Communication	Ethernet: UDP, Modbus TCP, Ethernet/IP. RS-485: Modbus RTU
Weight	15 kg (excluding cable)
Footprint (L x B x H)	19 cm x 19 cm x 20.5 cm
Enclosure material	AISI 316L
Operating temperature range	-20 to +40 degrees Celsius
Options	Magnetic Heading, Inclinometer / VRU version

**Versions and Options**

The MRU is also available in an inclinometer / VRU version without Heave/Surge/Sway output, which gives the same Roll & Pitch performance as the MRU, also in irregular coupled motions.

# MRU Specifications

	3000	6000	9000	Remarks
<b>Performance</b>				
Roll & Pitch	± 0.05°	± 0.02°	± 0.01°	RMS (dynamic)
Heave (real-time)	5.0 cm or 5.0 %	5.0 cm or 5.0 %	5.0 cm or 5.0 %	Whichever is greater for 0 to 25 s periods
Heading (optional)	± 0.5°	± 0.5°	± 0.5°	Magnetic heading
<b>Range</b>				
Rotation speed	± 150°/s	± 450°/s	± 450°/s	-
Acceleration	± 3 g	± 4 g	± 10 g	-
Heave	± 50 m	± 50 m	± 50 m	-
Roll/Pitch/Yaw	± 180° / ± 90° / ± 360°			-
Output frequency	0-100 Hz	0-100 Hz	0-100 Hz	Adjustable output frequencies
<b>Gyro output</b>				
Scale factor error	0.2% max/min	0.2% max/min	0.2% max/min	-
Angular rate noise	0.05°/s RMS	0.025°/s RMS	0.015°/s RMS	-
<b>Acceleration output</b>				
Acceleration noise	0.0025 m/s <sup>2</sup> RMS	0.002 m/s <sup>2</sup> RMS	0.0015 m/s <sup>2</sup> RMS	-
Acceleration accuracy	0.01 m/s <sup>2</sup> RMS	0.01 m/s <sup>2</sup> RMS	0.01 m/s <sup>2</sup> RMS	-
<b>Power &amp; Interface</b>				
Power consumption	6 W			-
Supply voltage	9-36 V DC (24 V nominal)			-
Internal storage	32 GB			-
Data protocols	Custom NMEA, ASCII and Binary, Atlas, Gyrocompas 1, Ifremer Victor, MDL, NORSUB 1-8, Simrad EM 3000, SMCA, SMCC, Tokimek PTVG, RDI ADCP, TSS1 and many more. Please refer to user manual.			-
Configuration protocols	GET/SET through telnet or serial port and web server based configuration SW			-
Time synchronization	Sync to host PC, Sync to NTP server, Sync to PPS			-


	3000	6000	9000	Remarks
<b>Environmental specifications</b>				
Storage temperature range	-40 to +85 degrees Celsius			-
Electromagnetic compatibility (immunity/emission)	IEC 60945/EN 60945			-
Vibration	IEC 60945/EN 60945			-
Max shock non-operational (10 ms peak)	2000 m/s <sup>2</sup> (half-sine 0.5 msec)			-
MTBF (computed)	100000 h			-

## Ultra-Low-Noise accelerometer

The ACC is high performance, ultra-low noise, and affordable. The ACC use state-of-the-art MEMS technology 3-axis accelerometers. The exceptional low noise density, velocity random walk (VRW) and bias instability make this accelerometer ideal for high demanding vibration monitoring applications.

The ACC can be mounted in a dry area (ACC Compact & ACC Marine), on a floating substructure in up to 50 m water depth (ACC Marine SW) and subsea up to 6000m (ACC Subsea) and offers a very cost-effective solution for demanding vibration monitoring applications.

Developed for monitoring of floating offshore wind platforms, offshore structures and subsea templates or any other structure with demanding vibration monitoring requirements. The accelerometer can be used in real time applications to monitor the integrity of the installation, as an input to a digital twin model of the structure or as an input for fatigue life analysis.

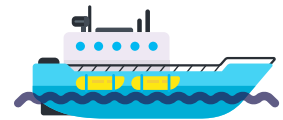
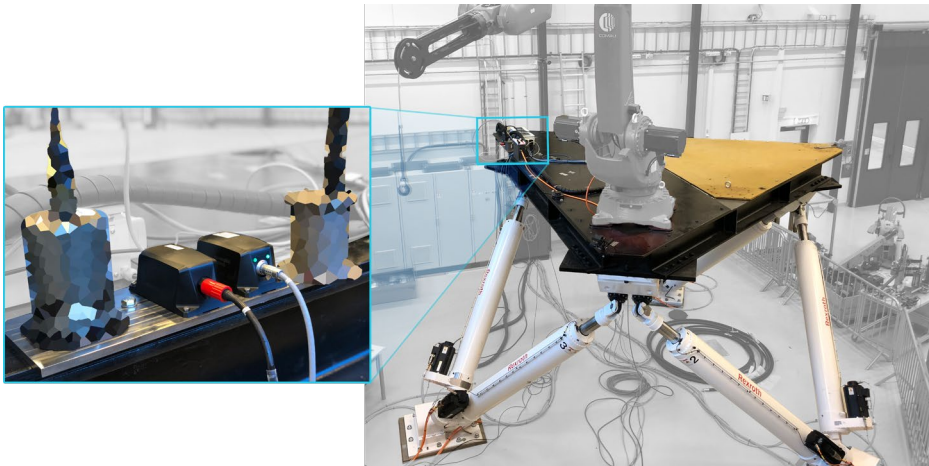
	 <b>Ultra-Low-Noise Accelerometer</b>
Range	± 15 g
Scale factor	6.00E-05 mg/LSB
Misalignment axis to axis	0.1 degs
Nonlinearity	0.03 %FS
Initial error	2 mg
Bias repeatability	3 mg
In run bias instability	0.2 µg
Velocity random walk (VRW)	0.00012 m/s/sqrt(h)
Noise density	0.7 µg/sqrt(Hz) RMS
Frequency bandwidth 3dB	400 Hz



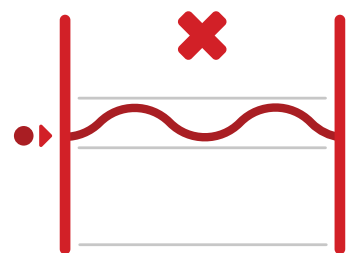
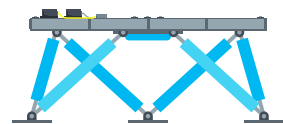
# Validated in real sea conditions

## Tested in real sea conditions

Many suppliers tend to present test data solely for simple regular motions observed in laboratory conditions. Unfortunately, vessels experience irregular and coupled motions at sea. While most sensors perform well in sine wave motion, only a select few excel in irregular sea conditions. Our MRUs stand out as they consistently deliver exceptional performance across all conditions.



Real Sea condntions



Lab conditions

3rd party test facility	Motion Lab, University of Agder Grimstad (Norway)
Motion reference platform	Bosch Rexroth eMotion-8000 hexapod with laser position measurements
Tested MRU	MRU Marine 6000
Tested scenarios	Regular and irregular sea-state conditions Based on real sea conditions Single and multi-axis coupled motions Motion periods from 3 to 25 seconds

This test verifies that the Norwegian Subsea MRUs meet the specifications and demonstrates typical MRU performance in realistic sea conditions.

Two Norwegian Subsea MRUs were mounted on top of a hexapod and the MRU output was compared to the reference measurements from the hexapod (truth).

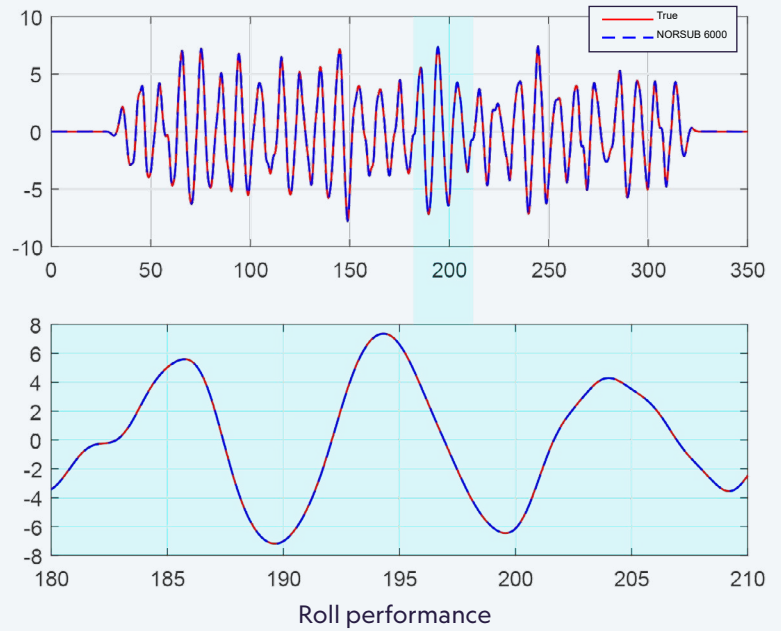
Both regular and irregular motion patterns were tested, with periods from 3 to 25 s and amplitudes from 0.1 to 0.8 m / 0 to 10 degrees. All degrees of freedom (DOFs) were tested individually and combined (coupled motions)

### Combined roll and pitch test

Irregular motion profile with significant amplitude of 5 degrees and peak period of 10 s.

The test starts and stops with the MRU in the horizontal position (0 degrees).

The roll and pitch RMS error is calculated over the entire test duration of 350 s.



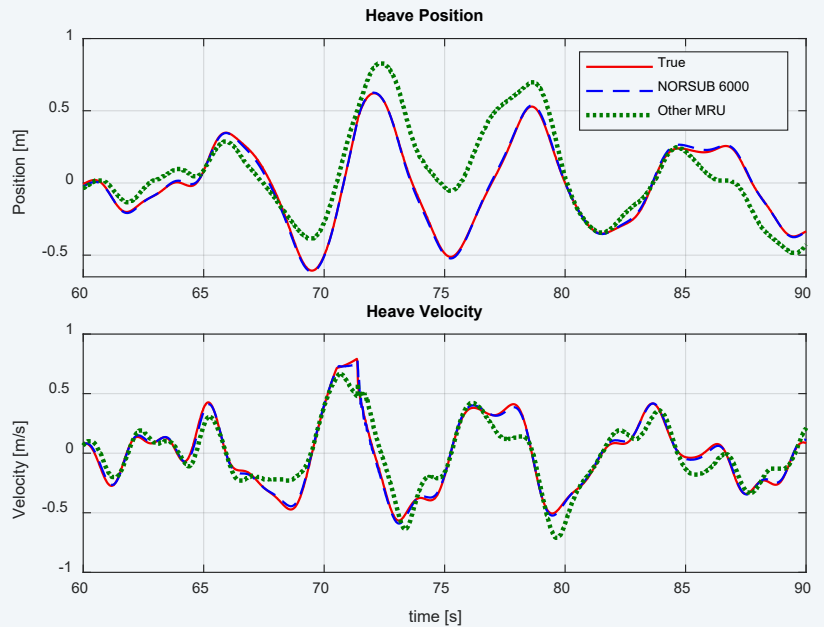
	Datasheet Specs	Test Results	Approved
Roll	0.02°	0.016°	✓
Pitch	0.02°	0.014°	✓

### Heave Test

The heave test has an irregular motion profile with a significant amplitude of 0.5 m and peak period of 7 s. The heave filter uses automatic estimation of significant amplitude and peak period to optimize the performance.

The heave RMS error is calculated over the entire test duration of 250s. As you can see, the results are very accurate.

For reference, an MRU from another brand, having the same Heave accuracy specifications, was included in the tests. This MRU performed well in sine waves, but in real sea conditions, this MRU was not able to provide useful results.

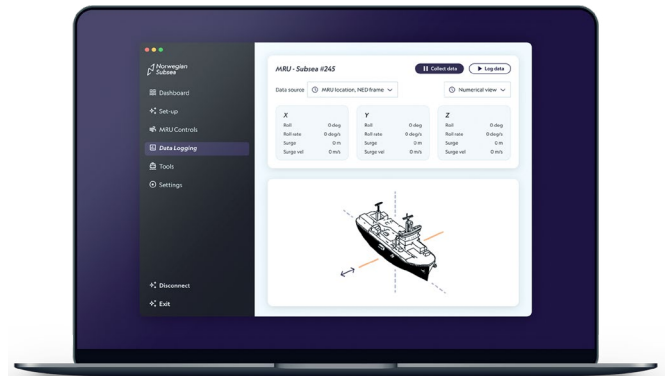


	Datasheet Specs	Test Results	Approved
Heave	0.05 m or 5.0%	0.017 m	✓
Heave Velocity	0.02 m/s or 3.0%	0.011 m/s	✓

# High accuracy, easy to use and no maintenance

## User friendly configuration

All MRUs and ACCs can be easily configured using the web based configurator. Here you can configure the communication ports, customize the output data protocol, configure the sensor installation parameters, or check the internal status. The software can also update the MRU firmware, log the sensor data to file, and plot output data. The configuration SW runs straight from the sensor, no downloads required.

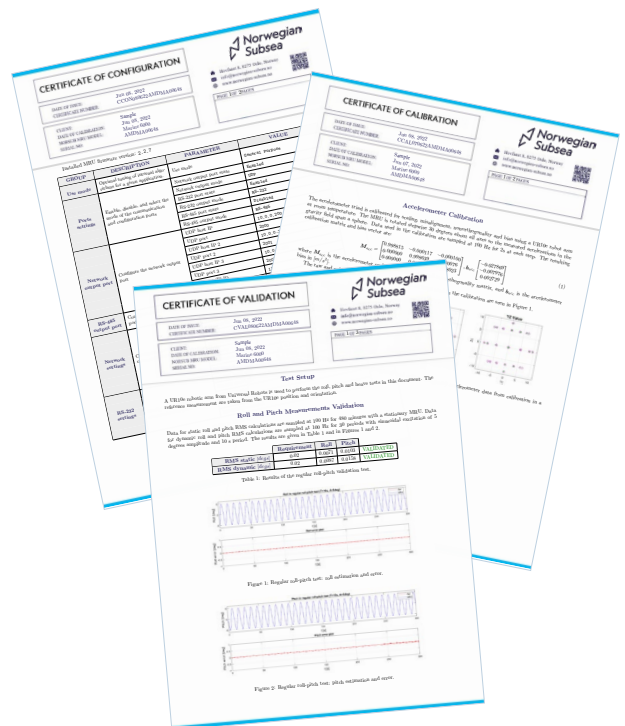


## Every sensor is calibrated, tested and validated

Every MRU is delivered with Configuration, Calibration, and Validation Certificates. All MEMS sensors are temperature calibrated so the sensor temperature does not influence the results. Every unit is calibrated and validated independently through a systematic sequence of rigorous tests in our labs.

## No recalibration

The calibration certificate is valid for 4 years and full product specifications are maintained in this period under normal operating conditions. A slightly lower specification for Roll & Pitch is maintained during the lifetime of the sensor. For most applications, therefore no recalibration is required during the lifetime of the sensor.



## Roll / pitch accuracy

	With recalibration	Without recalibration
<b>3000</b>	0.05°	0.1°
<b>6000</b>	0.02°	0.05°
<b>9000</b>	0.01°	0.035°

## Retrofit of existing MRU

Many vessels have MRUs installed that need frequent recalibration and repair. Or are end-of-life since support and recalibration services are no longer available. For most applications, our MRUs do not require recalibration during its lifetime. This is because our MRUs use the latest generation high-end MEMS sensors that are extremely stable.

monitoring can really benefit from the retrofit solution as you can switch to an affordable MRU that does not require recalibration.

## Typical applications for retrofit solution

Any application that uses a motion reference unit should consider our retrofit solution. But especially applications such as AHC, dynamic positioning and helideck motion

## Export license

Our MRUs do not require an export license as they are not on the list of dual use items as per EU regulations.

# About us



Norwegian Subsea is a leading provider of high-performance Motion Reference Units (MRU) and motion sensors for marine, subsea and offshore wind applications. Accurate and reliable measurements for control and monitoring purposes.

Since its establishment in 2014, Norwegian Subsea has rapidly emerged as a trusted global supplier of motion sensors. Serving diverse industries such as ship motion monitoring, hydrography, green energy, and subsea oil production, our satisfied customers testify to the reliability and quality of our solutions.

Our mission is to develop exceptional and cost-effective motion sensors tailored for the marine, land, and subsea

sectors. Through the fusion of advanced sensor algorithms, state-of-the-art MEMS sensors, and top-notch hardware, we create superior products. Rigorous testing in cutting-edge laboratories and real-world environments ensures the performance and dependability of our sensors.

With our headquarters situated in Oslo, Norway, Norwegian Subsea remains dedicated to providing innovative solutions that address the evolving needs of our customers in motion monitoring and beyond.

Norwegian Subsea is headquartered at Harbitzalléen 2A, 0275 Oslo, Norway.

## Contact information

### **General Enquiries**

info@norwegian-subsea.no  
(+47) 406 35 500

### **Sales Enquiries**

sales@norwegian-subsea.no  
(+47) 406 35 200

### **Technical Support**

support@norwegian-subsea.no



# Selected customer references

## Helideck Monitoring Systems



## Floating wind lidar buoys



## Motion Compensation of cranes, gangways, LARS & winches



## Hydrography

- Our MRUs are used with the following sonar systems



## Dynamic positioning

- Our MRUs are used with the following DP systems



## Wave radar



## Other references







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